

Forest Biosecurity Workshop 2015

Remote Sensing – What we can do now, What is possible in future



Technology

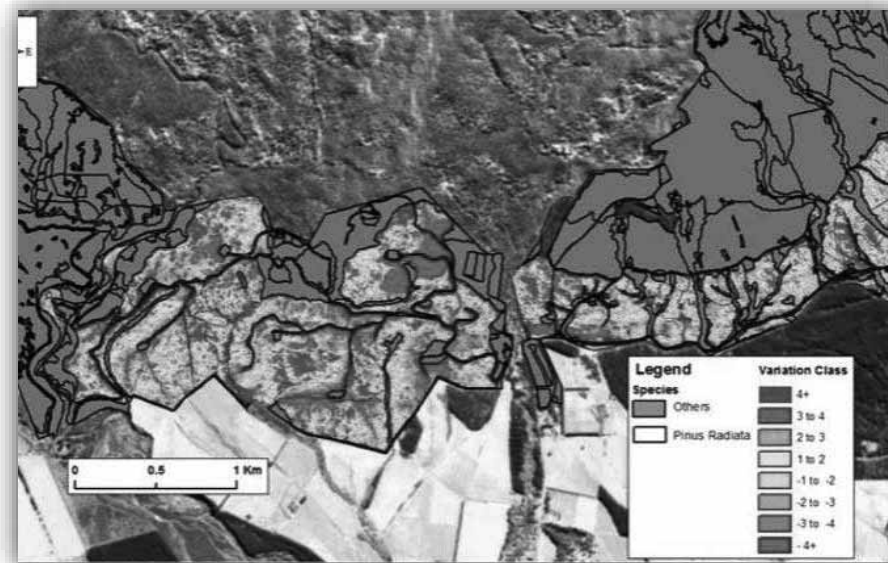
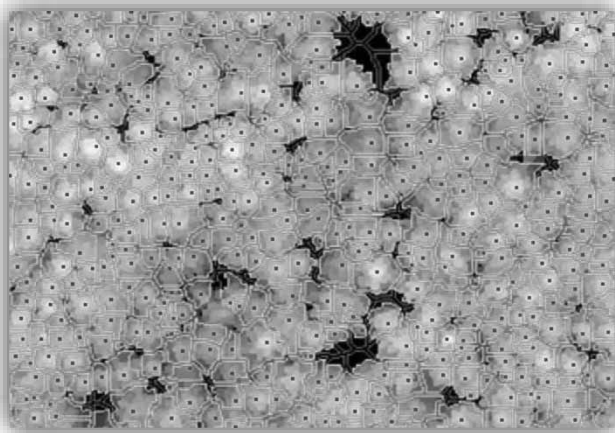
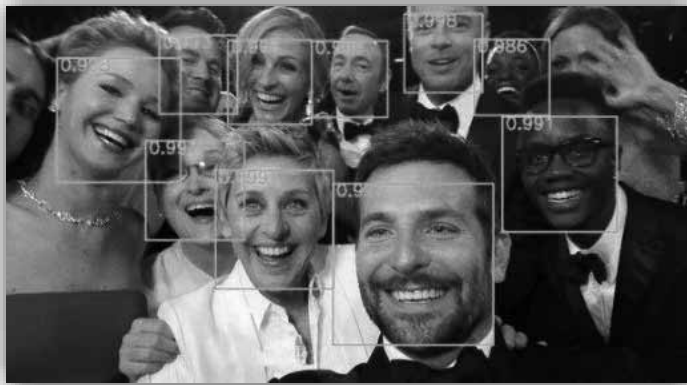


Add
Value



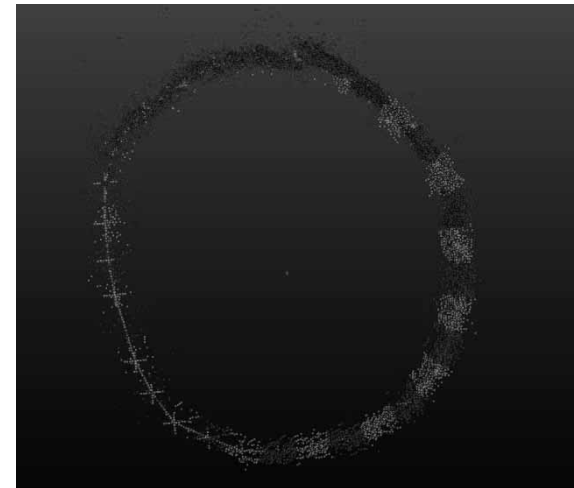
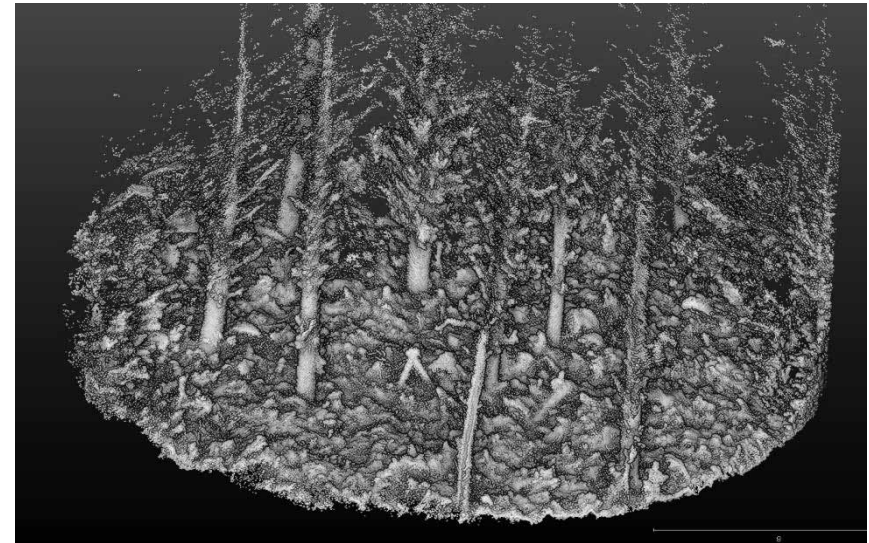
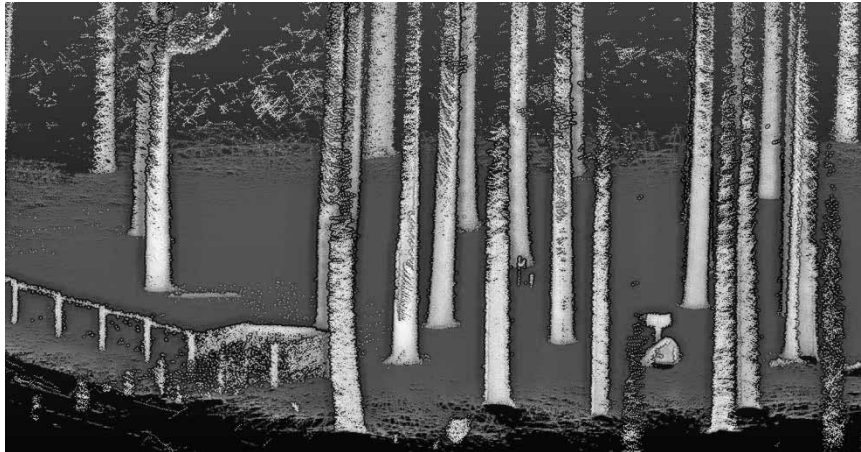
What can we do Today

- Image Analysis



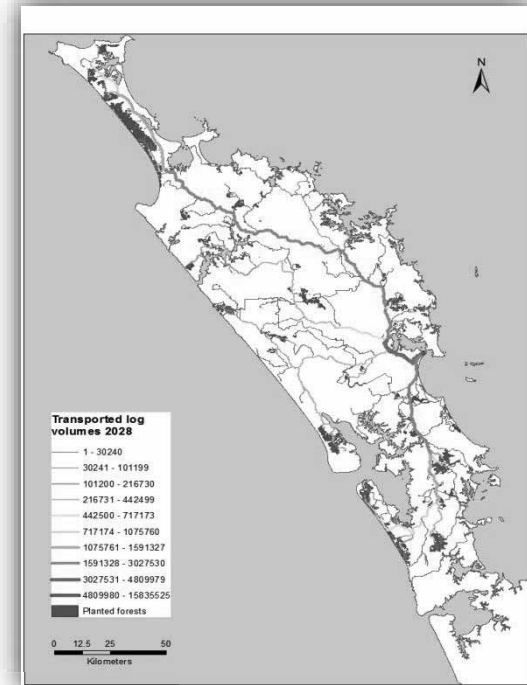
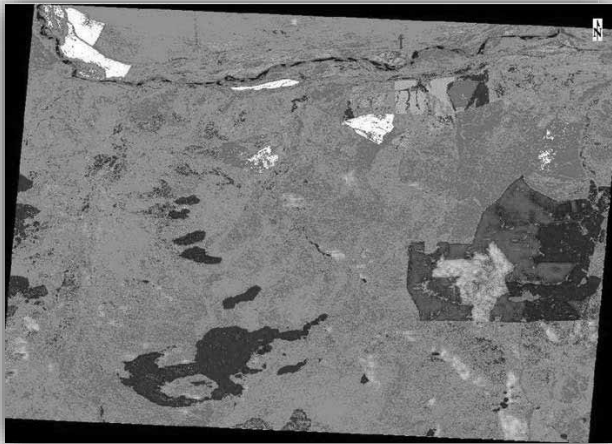
What can we do Today

- Point Clouds



What can we do Today?

- Decision support systems



What could we do Tomorrow?

- Satellite
 - Higher resolution (World view 3)
 - Platform as a service
 - Google Earth
 - LiDAR Satellite
 - HD Video

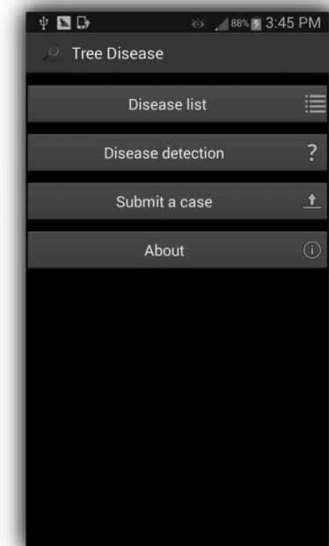
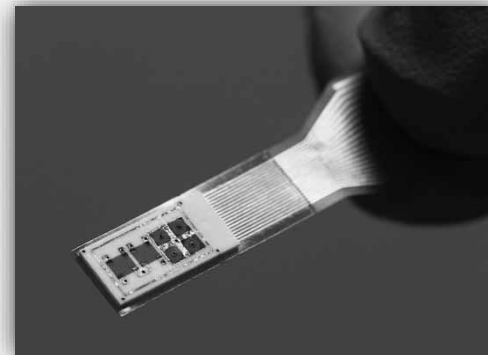
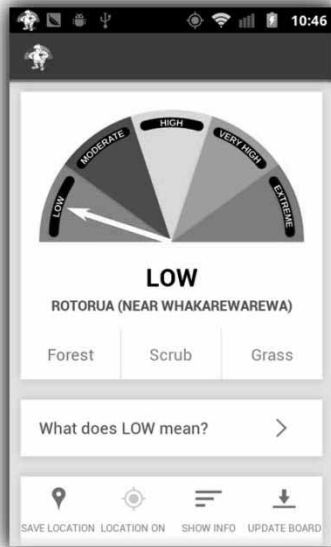


What could we do Tomorrow?

- Skybox
- <https://www.youtube.com/watch?v=fCrB1t8MncY>

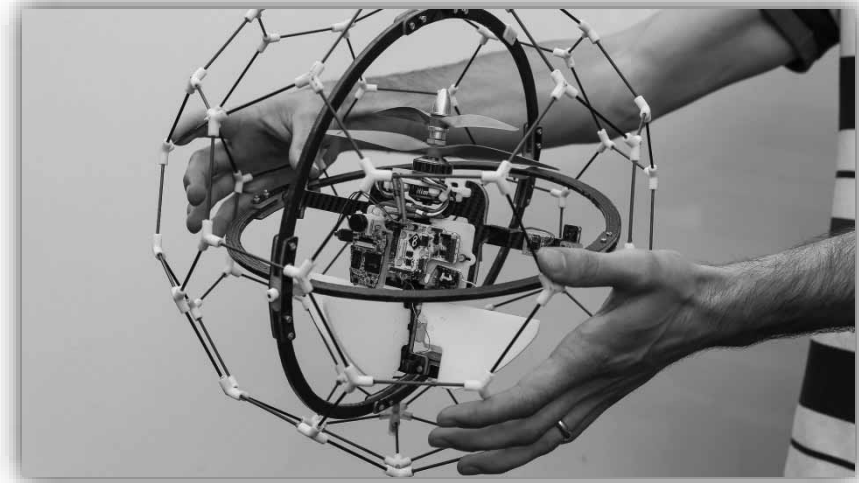
What could we do Tomorrow?

- Mobile as a data source
 - Smart Phones – a huge array of sensors
 - Sensor Networks – A sensor on every tree? Trap?
 - Internet of Things



What could we do Tomorrow?

- UAV's
 - Just a platform...
- Scion example
 - Video
 - LiDAR
 - Near Infra-Red
 - Hyper-Spectral



What could we do Tomorrow?

- Scion Example
 - Autonomous flight under canopy
 - Autonomous forest edge following
 - Target Spraying
 - Mid range surveillance (500-1000Ha)
 - LiDAR acquisition at mid range
 - Robotic Sampling arm (Auckland University student)

What could we do Tomorrow?

- Systems approach
 - Not just one technology, rather a combination of them
 - Combining technologies to drive a decision, response
 - Weather
 - Satellite
 - UAV
 - Sensor network
 - Mobile
 - Boots on the ground
 - A move towards real time information and monitoring.

Summary

- Systems approach
 - Not just about one technology on it's own
- Major advances in data acquisition
- Major advances in decision support systems
- Need to be cautious of chasing the hype

Thank you

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“Sadly, it's much easier to create a desert than a forest.”

James Lovelock

Scenario

1. A moth flies past a pheromone detection sensor
2. The trap sends out a notification saying “we have a problem”
3. A swarm of UAV’s is deployed to the area, and people in the area are notified
4. In the office a system has collated all the information for a 3km block around the site. Weather data, terrain information, historical data, and imagery are pulled together to generate a 3d “world”.
5. Biosecurity personnel use their 3d headsets to move through this world to see what the UAV swarm is seeing, look at the simulations in real time, and make a decision about next steps.

Scenario

